

Network Objects

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Plan for Today

- XBee Firmware
- XBee I/O Workshop
- API Mode
- Readings & Assignments

XBee Firmware

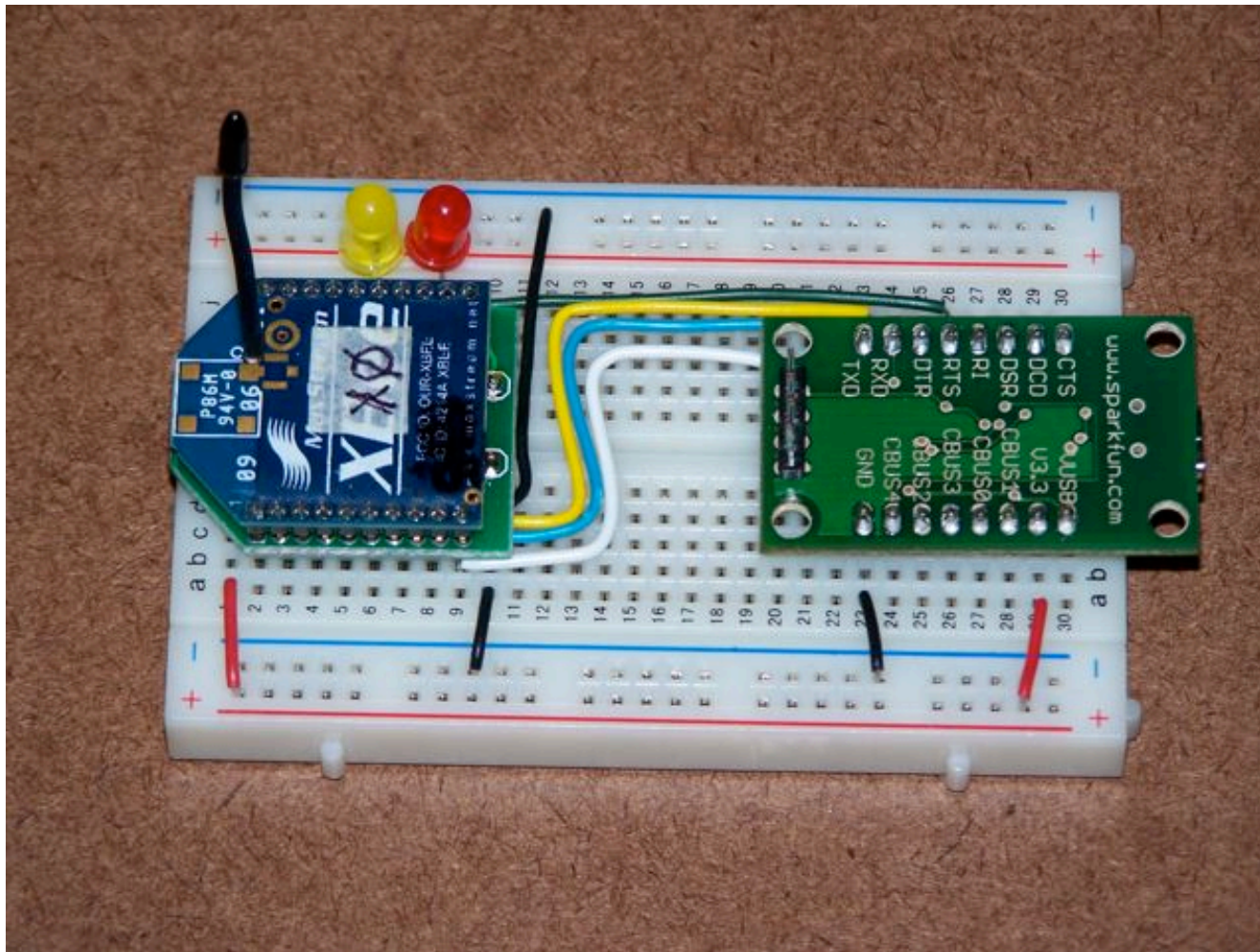
X-CTU

- Features:
 - terminal
 - firmware
 - configuration
 - tests
- Demo: updating firmware

Firmware Upload

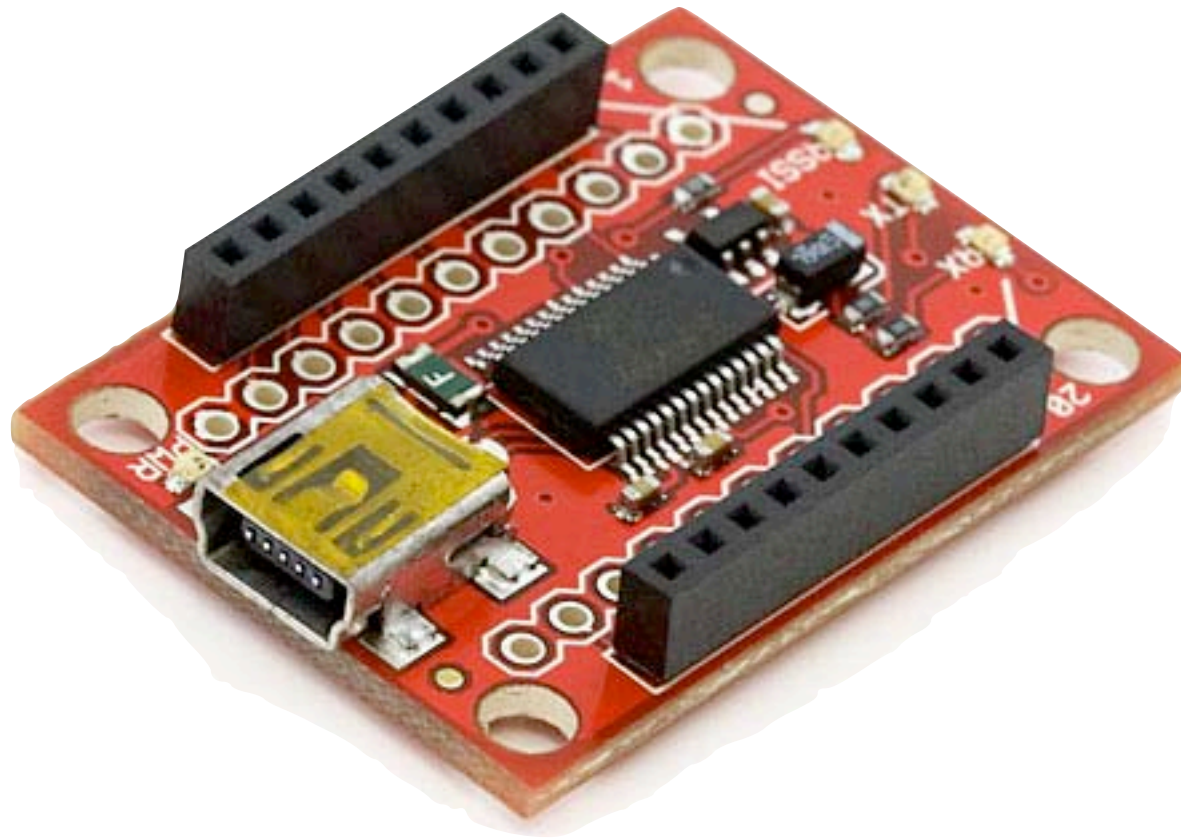
- X-CTU Program
- Special circuit, dongle or development board
- Firmware, command interface, test area, terminal all Windows-only

Firmware Upload Board



SparkFun part#PCB-FT232RL, wired to RX, TX, RTS, DTR, 3.3V, Gnd

XBee Explorer



XBee I/O mode

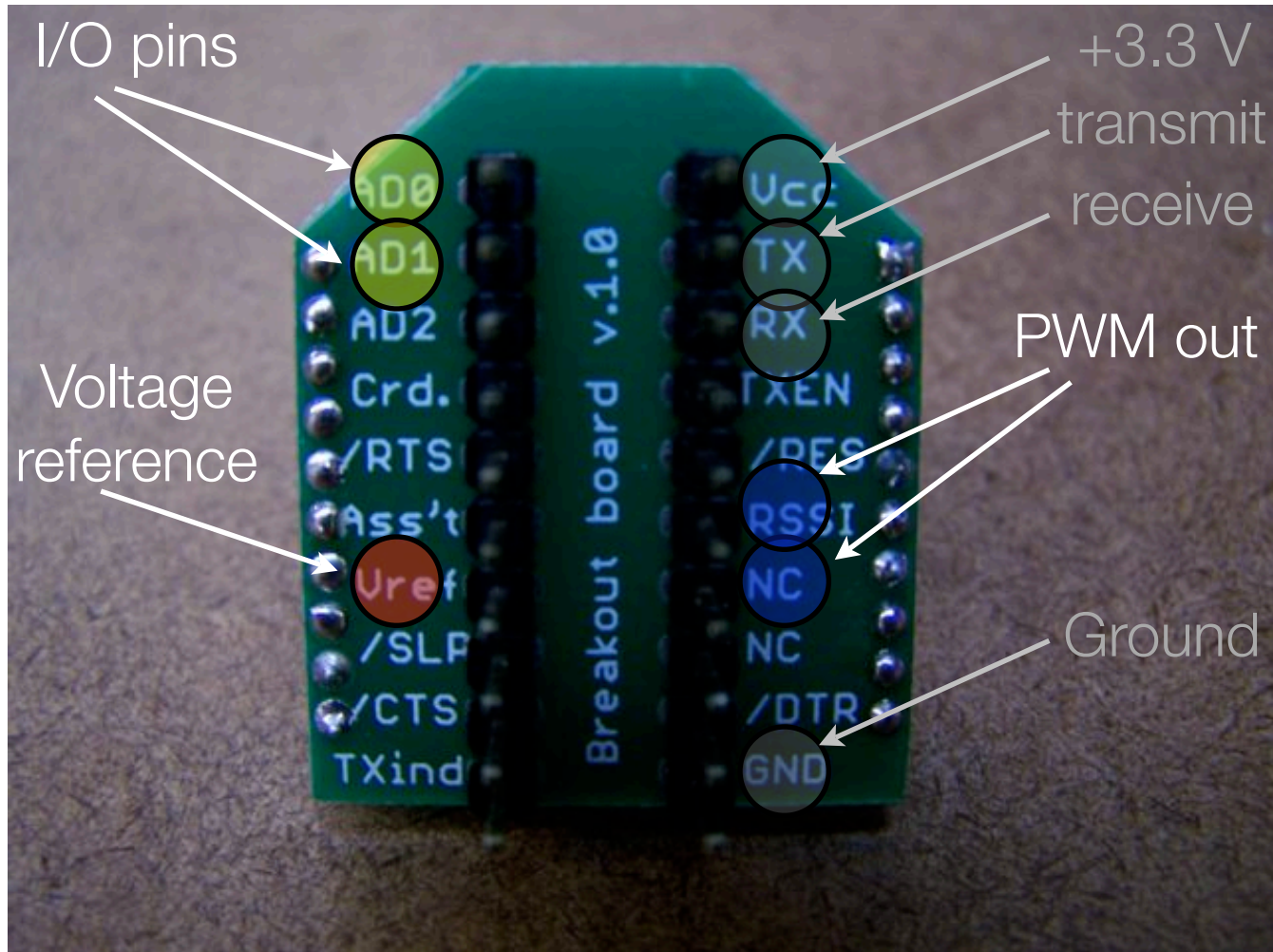
I/O Why

- Why:
 - Save space, save power, save weight and save money
 - Reduce complications
- Why not:
 - Limited inputs/outputs
 - No access to logic
 - Each radio must be manually configured

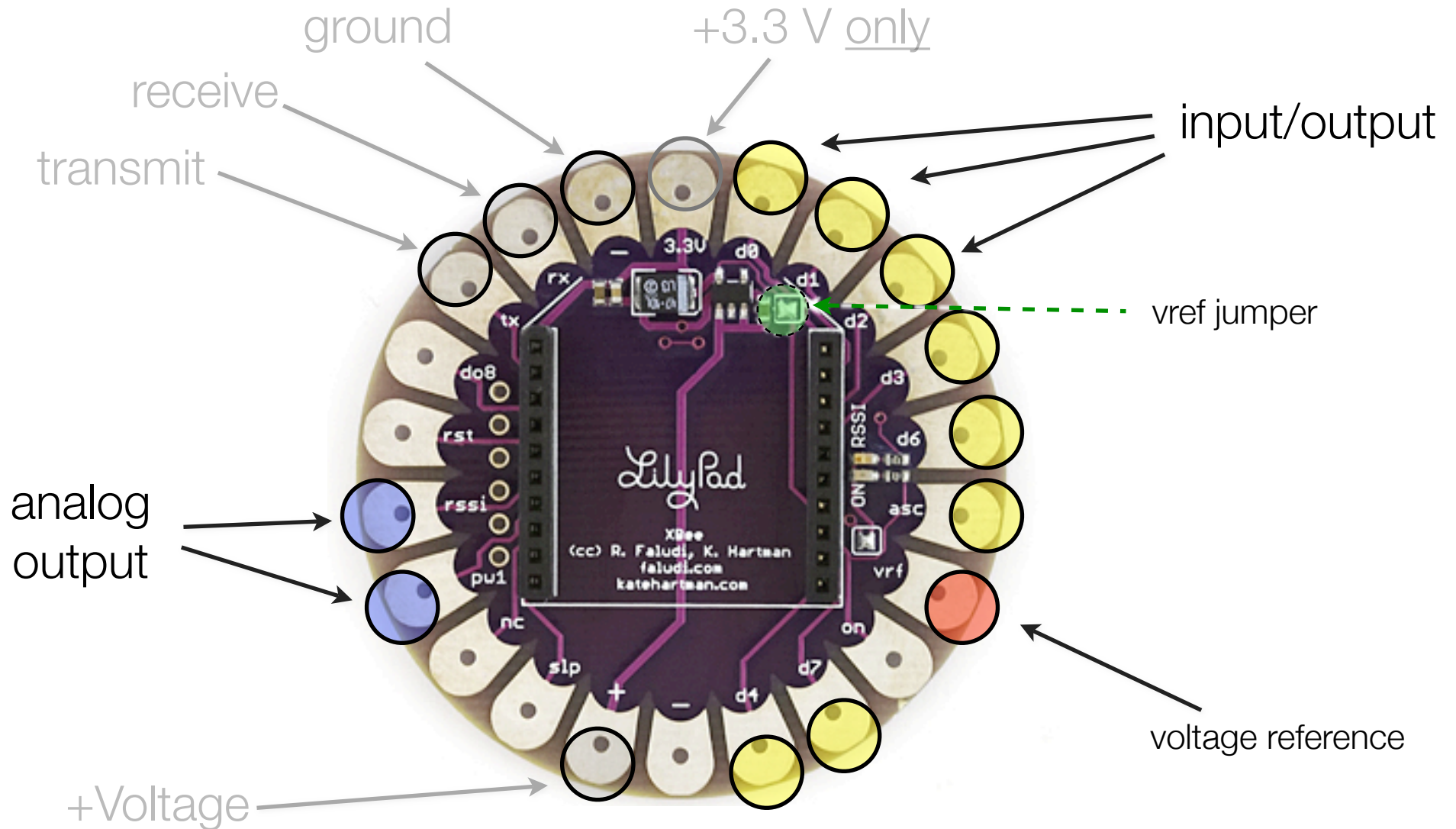
I/O Intro

- For simple input and/or output
- Eight digital input/outputs
- One additional digital output
- Seven analog inputs
- Two analog outputs
- But not all at once! Pins are shared.

Input/Output Wiring



Input/Output Wiring



I/O AT Commands

- ATD0...D8 -> configure pins for I/O
- ATIR -> sample rate
- ATIT -> samples before transmit
- ATP0...P1 -> PWM configuration
- ATIU -> I/O output enable (UART)
- ATIA -> I/O input address

Example Configuration

- ATID3456 (PAN ID)
ATMY1 my address 1
ATDL2 destination address 2
ATD02 pin 0 in analog in mode
ATD13 pin 1 in digital in mode
ATIR14 sample rate 20 milliseconds (hex 14)
ATIT5 samples before transmit 5
ATWR write settings to firmware

- ATID3456 (PAN ID)
ATMY2 my address 2
ATDL1 destination address 1
ATP02 PWM 0 in PWM mode
ATD15 pin 1 in digital out high mode
ATIU1 I/O output enabled
ATIA1 I/O input from address 1
ATWR write settings to firmware

I/O Workshop

- Set up input and output radios with sensors
- Transmit values without any external microcontroller

Common XBee Mistakes

- <http://www.faludi.com/projects/common-xbee-mistakes/>

Protocols

- Sending
- Flow control
- Call / response
- Broadcast
- Start / stop
- Checksums
- Collisions

XBee API Mode

API Mode

- Application Programming Interface

- “An application programming interface (API) is a source code interface that an operating system or library provides to support requests for services to be made of it by computer programs.”

<http://www.computerworld.com/action/article.do?command=viewArticleBasic&articleId=43487>

- XBees in API mode are ready to talk to computers and microcontrollers

- structured
- predictable
- reliable



API Structure

- Used in serial communications with the XBee radio
- Frames of data
 - envelope structure contains data with metadata inside a constrained format
- Radio must be in API Mode
 - AT command ATAP 1 on Series 1 radios
 - API firmware on Series 2 radios

Why API

- Rather than:

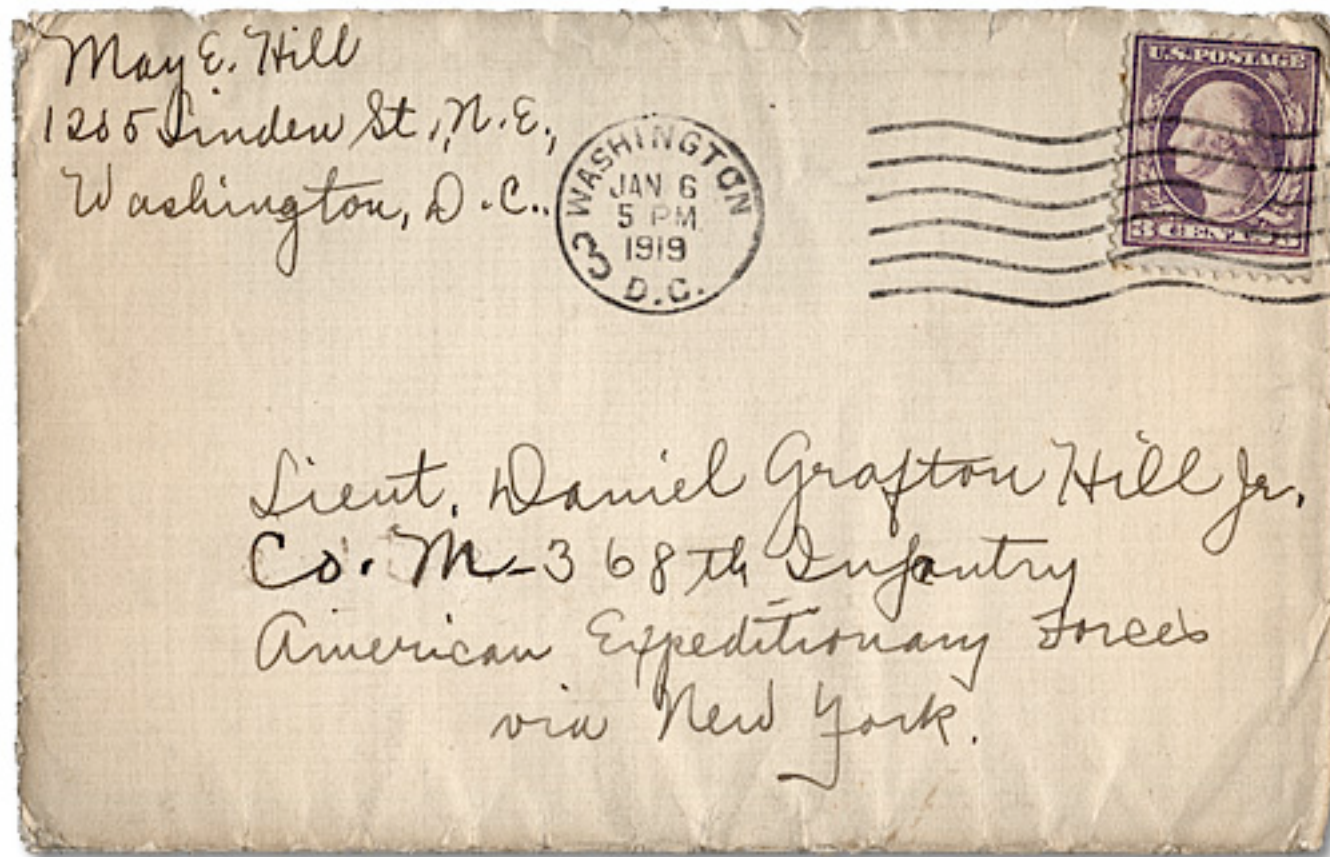
```
delay(1100);  
// put the XBee in command mode  
Serial.print("+++");  
delay(1100);  
if (checkFor("OK", 1000)) {  
    Serial.println("ATID7777,CN");  
    if (checkFor("OK", 1000)) {  
        // if an OK was received then continue  
        debugPrintln("SetupOK");  
        success = true;  
    }  
}
```

- With a library you just write:

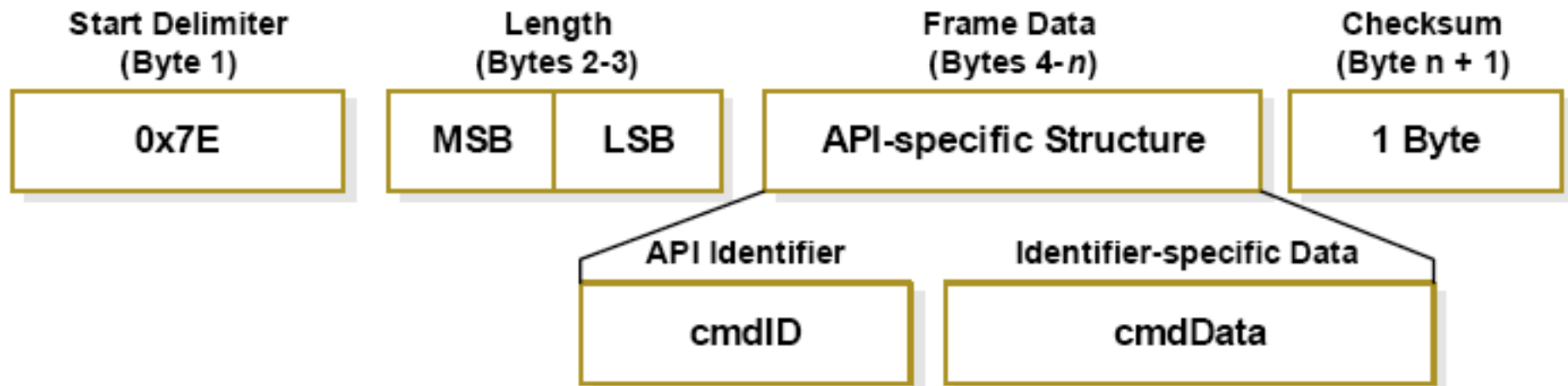
```
sendCommand(ID, 0x7777);
```

Envelope Has:

- From address, to address, outside, inside, size, contents, error check



API Basic Frame Envelope



Start Byte

- 0x7E --> also known as the tilde in ASCII: ~
- First thing to do is look for it:

```
// ARDUINO VERSION:
if (Serial.available() > 0) { // if a byte is waiting in the buffer
  inByte = Serial.read(); // read a byte from the buffer
  if (inByte == 0x7E) {
    // we're at the start of an API frame!
    // add more code here
  }
}
```

```
// PROCESSING VERSION:
if (port.available() > 0 {
  int inByte = port.read();
  if (inByte == 0x7E) {
    // we're at the start of an API frame!
    // add more code here
  }
}
```


Length Bytes

- MSB: the Most Significant Byte
 - the big part of the number
- LSB: the Least Significant Byte
 - the small part of the number
- bit shift MSB to the right and add it to LSB

```
// PROCESSING VERSION:  
int lengthMSB = port.read(); // high byte for length of packet  
int lengthLSB = port.read(); // low byte for length of packet  
  
int lengthTotal = (lengthMSB << 8) + lengthLSB; // bit shift and add for total
```

API Identifier

- Specifies the remaining structure of the frame
 - modem status: 0x8A
 - AT command (immediate): 0x08
 - AT command (queued): 0x09
 - AT command response: 0x88
 - TX request (64 bit): 0x00
 - TX request (16 bit): 0x01
 - TX status response: 0x89
 - RX packet (64 bit): 0x80
 - RX packet (16 bit): 0x81
 - RX packet I/O data (64 bit): 0x82
 - RX packet I/O data (16 bit): 0x83

```
// PROCESSING VERSION:  
int API_ID = port.read(); // API Identifier indicates type of packet received
```

Identifier-specific Data

- Structures are different for each API identifier and might include:
 - addressing information (333B)
 - status information (received OK)
 - source information (broadcast packet)
 - unstructured data (“Hello World, this is Rob!”)
 - structured data (typically for I/O packets)

Checksum

- Simple check to detect errors
- To calculate: Not including frame delimiters and length, add all bytes keeping only the lowest 8 bits of the result and subtract from 0xFF.
- To verify: Add all bytes (include checksum, but not the delimiter and length). If the checksum is correct, the sum will equal 0xFF.

```
// PROCESSING VERSION:
int localChecksum = (API_ID + addrMSB + addrLSB + RSSI + options + dataSum);

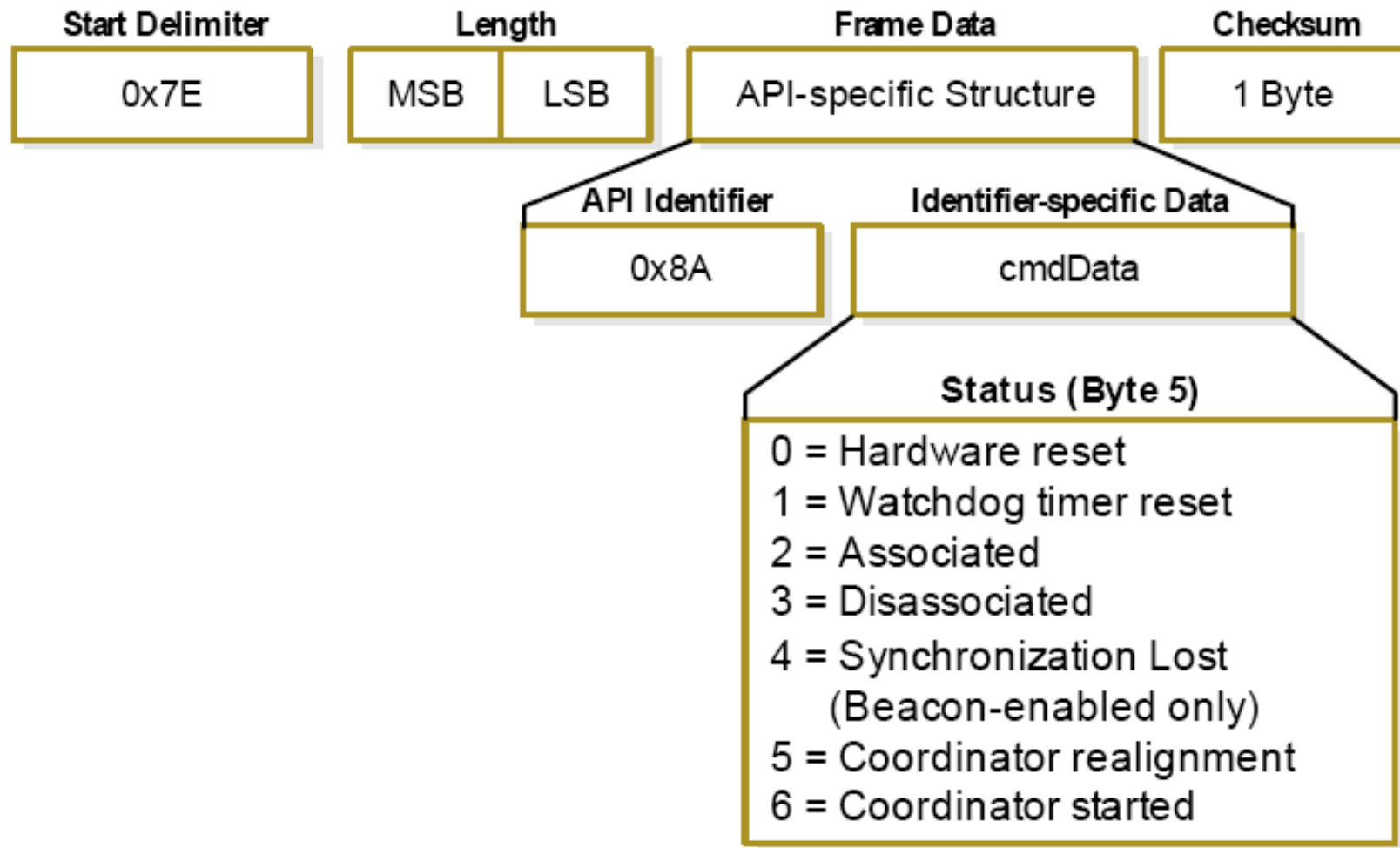
int checksum = port.read();
localChecksum = byte(0xFF -localChecksum);

if ( (byte) checksum - localChecksum == 0) {
    returnVal = dataADC[0];
}
else {
    print("\n\nchecksum error!  " + "\n\n");
}
```

Many Kinds of Envelopes



Modem Status



AT Command

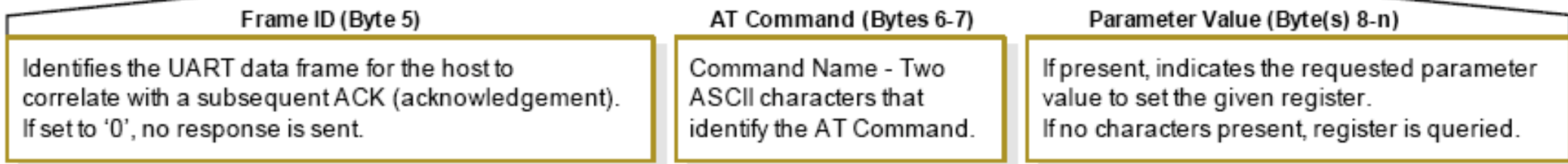
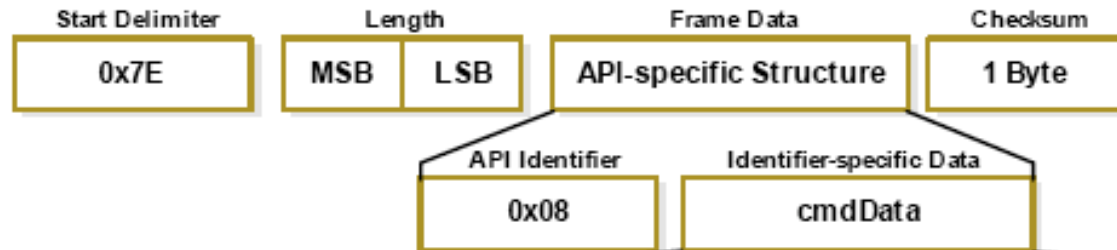
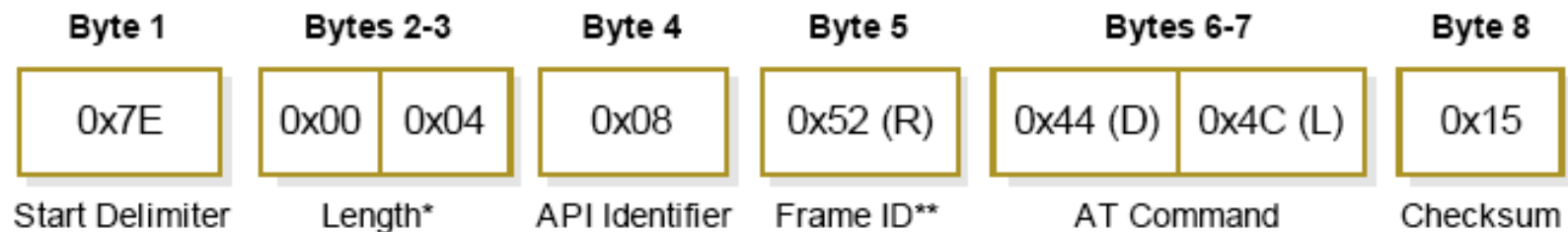
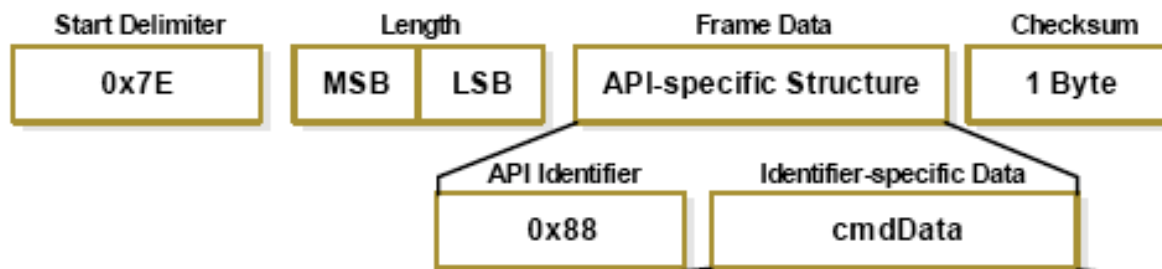


Figure 3-06. Example: API frames when reading the DL parameter value of the module.



AT Response

- Frame ID for the response is the same as the matching AT Command request



Frame ID (Byte 5)

Identifies the UART data frame being reported.
Note: If Frame ID = 0 in AT Command Mode, no AT Command Response will be given.

AT Command (Bytes 6-7)

Command Name - Two ASCII characters that identify the AT Command.

Status (Byte 8)

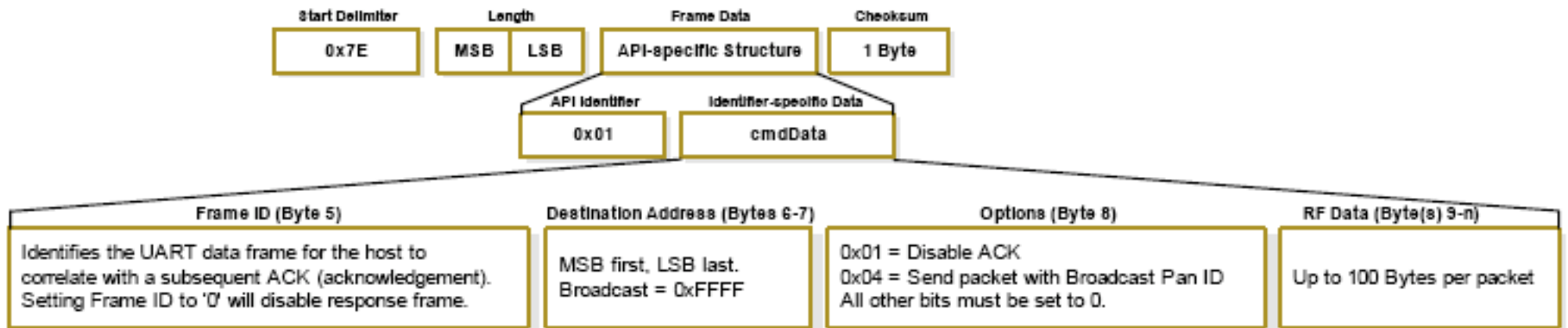
0 = OK
1 = ERROR

Value (Byte(s) 9-n)

The HEX (non-ASCII) value of the requested register

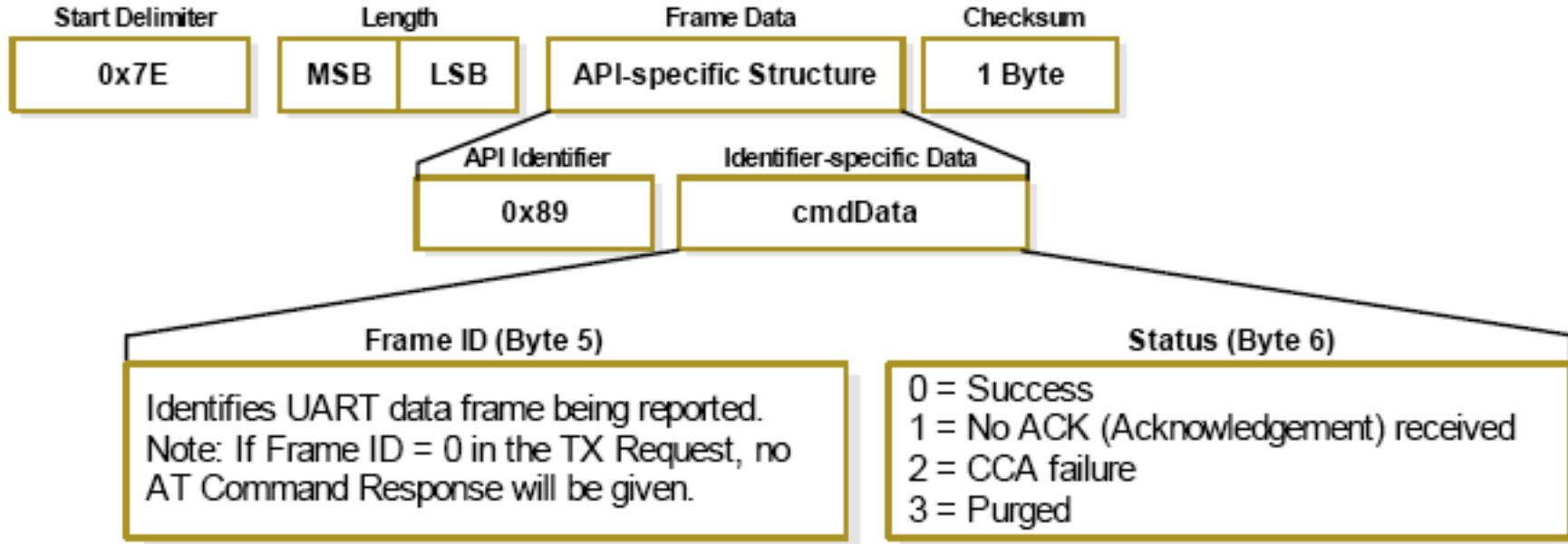
TX (Transmit) Request

- Remember that this is a request
- Also need to check for results by Frame ID



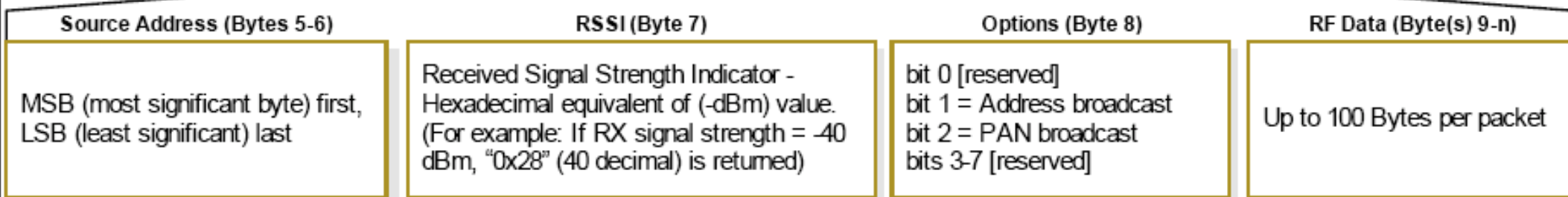
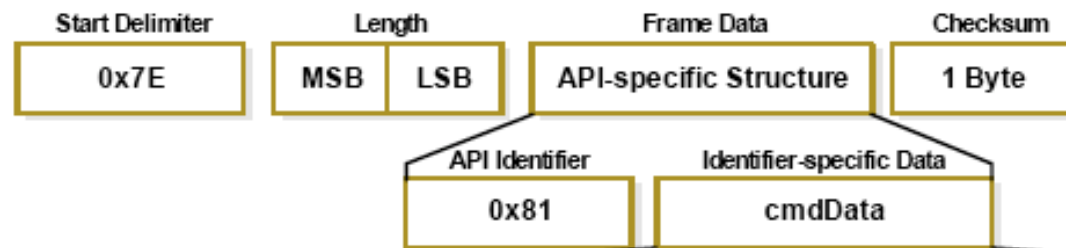
TX Status (Results)

- See if your message was transmitted or not
- Use your Frame ID to see which message is being described



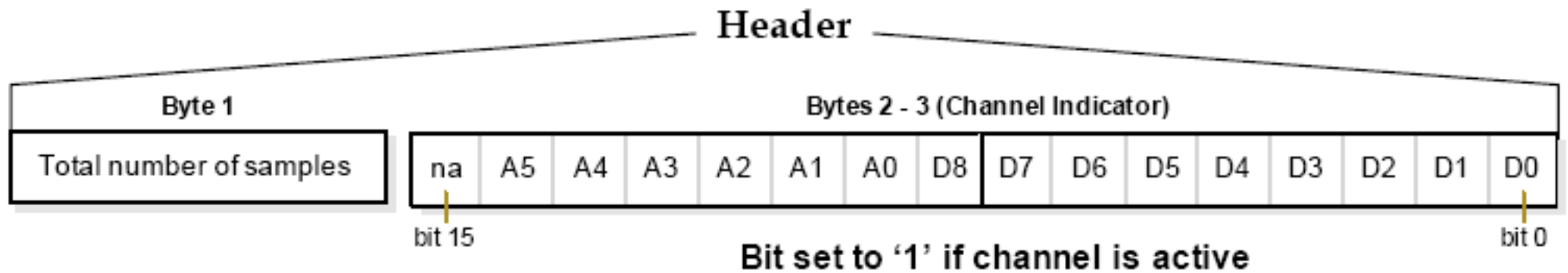
RX Packet (16 bit addressing)

- Maximum of 100 bytes of data per packet
- RF Data section is basis for I/O packets



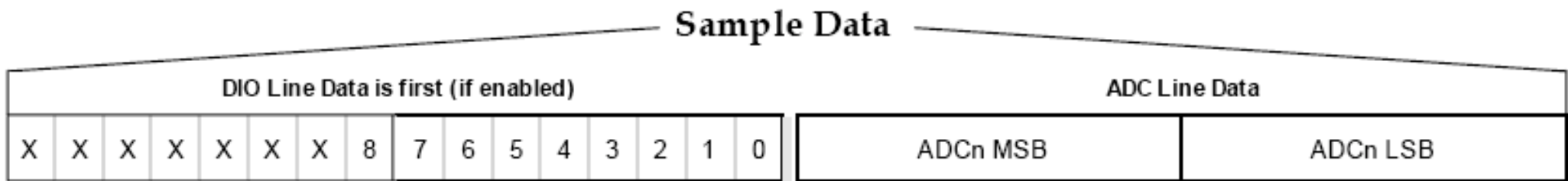
I/O Data Header

- Inside the RF Data section of the RX Packet
 - Total number of samples set with ATIS
 - Channels set with ATD0...9



I/O Data Sample

- Follows the header
- Two bytes of digital data IF ANY DIGITAL CHANNELS ENABLED followed by...
- ...two bytes for EACH analog channel enabled...
- ...then repeats for each sample



- How many bytes if ATIS5 ATD02 ATD12 ATD23?

I/O Code: Basic

- Fixed parameters make for easier programming
- Assume we are just reading a single sample of one ADC channel at a time:

```
// PROCESSING VERSION:
int totalSamples = port.read(); // this is the number of samples we're receiving
int channelIndicatorHigh = port.read(); // this tells us which analog channels
    // are in use (and one digital channel)
int channelIndicatorLow = port.read(); // this tells us which digital channels
    // are in use.

int dataADCMSB = port.read(); // read in the most significant ADC byte
int dataADCLSB = port.read(); // read in the least significant ADC byte
int dataADC = (dataADCMSB << 8) + dataADCLSB; // bit shift the MSB into
    // position and add it to the LSB

    print(dataADC); // print the information
}
```

Readings and Assignments

- Assignment
 - Final Project